

CHAPTER

DC Biasing—BJTs

4.1 INTRODUCTION

The analysis or design of a transistor amplifier requires a knowledge of both the dc and ac response of the system. Too often it is assumed that the transistor is a magical device that can raise the level of the applied ac input without the assistance of an external energy source. In actuality, the improved output ac power level is the result of a transfer of energy from the applied dc supplies. The analysis or design of any electronic amplifier therefore has two components: the dc portion and the ac portion. Fortunately, the superposition theorem is applicable and the investigation of the dc conditions can be totally separated from the ac response. However, one must keep in mind that during the design or synthesis stage the choice of parameters for the required dc levels will affect the ac response, and vice versa.

The dc level of operation of a transistor is controlled by a number of factors, including the range of possible operating points on the device characteristics. In Section 4.2 we specify the range for the BJT amplifier. Once the desired dc current and voltage levels have been defined, a network must be constructed that will establish the desired operating point—a number of these networks are analyzed in this chapter. Each design will also determine the stability of the system, that is, how sensitive the system is to temperature variations—another topic to be investigated in a later section of this chapter.

Although a number of networks are analyzed in this chapter, there is an underlying similarity between the analysis of each configuration due to the recurring use of the following important basic relationships for a transistor:

$$V_{BE} = 0.7 \text{ V}$$
 (4.1)

$$V_{BE} = 0.7 \text{ V}$$

$$I_E = (\beta + 1)I_B \cong I_C$$

$$I_C = \beta I_B$$

$$(4.1)$$

$$(4.2)$$

$$I_C = \beta I_B \tag{4.3}$$

In fact, once the analysis of the first few networks is clearly understood, the path toward the solution of the networks to follow will begin to become quite apparent. In most instances the base current I_B is the first quantity to be determined. Once I_B is known, the relationships of Eqs. (4.1) through (4.3) can be applied to find the remaining quantities of interest. The similarities in analysis will be immediately obvious as we progress through the chapter. The equations for I_B are so similar for a num-



ber of configurations that one equation can be derived from another simply by dropping or adding a term or two. The primary function of this chapter is to develop a level of familiarity with the BJT transistor that would permit a dc analysis of any system that might employ the BJT amplifier.

4.2 OPERATING POINT

The term biasing appearing in the title of this chapter is an all-inclusive term for the application of dc voltages to establish a fixed level of current and voltage. For transistor amplifiers the resulting dc current and voltage establish an operating point on the characteristics that define the region that will be employed for amplification of the applied signal. Since the operating point is a fixed point on the characteristics, it is also called the quiescent point (abbreviated Q-point). By definition, quiescent means quiet, still, inactive. Figure 4.1 shows a general output device characteristic with four operating points indicated. The biasing circuit can be designed to set the device operation at any of these points or others within the active region. The maximum ratings are indicated on the characteristics of Fig. 4.1 by a horizontal line for the maximum collector current $I_{C_{\max}}$ and a vertical line at the maximum collector-to-emitter voltage $V_{CE_{\max}}$. The maximum power constraint is defined by the curve $P_{C_{\max}}$ in the same figure. At the lower end of the scales are the cutoff region, defined by $I_B \leq 0$ μ A, and the saturation region, defined by $V_{CE} \leq V_{CE_{\max}}$.

The BJT device could be biased to operate outside these maximum limits, but the result of such operation would be either a considerable shortening of the lifetime of the device or destruction of the device. Confining ourselves to the *active* region, one can select many different operating areas or points. The chosen *Q*-point often depends on the intended use of the circuit. Still, we can consider some differences among the

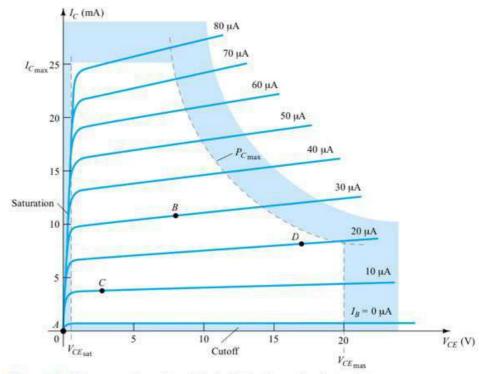


Figure 4.1 Various operating points within the limits of operation of a transistor.



various points shown in Fig. 4.1 to present some basic ideas about the operating point and, thereby, the bias circuit.

If no bias were used, the device would initially be completely off, resulting in a Q-point at A—namely, zero current through the device (and zero voltage across it). Since it is necessary to bias a device so that it can respond to the entire range of an input signal, point A would not be suitable. For point B, if a signal is applied to the circuit, the device will vary in current and voltage from operating point, allowing the device to react to (and possibly amplify) both the positive and negative excursions of the input signal. If the input signal is properly chosen, the voltage and current of the device will vary but not enough to drive the device into cutoff or saturation. Point C would allow some positive and negative variation of the output signal, but the peakto-peak value would be limited by the proximity of $V_{CE} = 0 \text{ V}/I_C = 0 \text{ mA}$. Operating at point C also raises some concern about the nonlinearities introduced by the fact that the spacing between I_B curves is rapidly changing in this region. In general, it is preferable to operate where the gain of the device is fairly constant (or linear) to ensure that the amplification over the entire swing of input signal is the same. Point B is a region of more linear spacing and therefore more linear operation, as shown in Fig. 4.1. Point D sets the device operating point near the maximum voltage and power level. The output voltage swing in the positive direction is thus limited if the maximum voltage is not to be exceeded. Point B therefore seems the best operating point in terms of linear gain and largest possible voltage and current swing. This is usually the desired condition for small-signal amplifiers (Chapter 8) but not the case necessarily for power amplifiers, which will be considered in Chapter 16. In this discussion, we will be concentrating primarily on biasing the transistor for small-signal amplification operation.

One other very important biasing factor must be considered. Having selected and biased the BJT at a desired operating point, the effect of temperature must also be taken into account. Temperature causes the device parameters such as the transistor current gain (β_{ac}) and the transistor leakage current (I_{CEO}) to change. Higher temperatures result in increased leakage currents in the device, thereby changing the operating condition set by the biasing network. The result is that the network design must also provide a degree of temperature stability so that temperature changes result in minimum changes in the operating point. This maintenance of the operating point can be specified by a stability factor, S, which indicates the degree of change in operating point due to a temperature variation. A highly stable circuit is desirable, and the stability of a few basic bias circuits will be compared.

For the BJT to be biased in its linear or active operating region the following must be true:

- The base-emitter junction must be forward-biased (p-region voltage more positive), with a resulting forward-bias voltage of about 0.6 to 0.7 V.
- 2. The base-collector junction *must* be reverse-biased (*n*-region more *p*ositive), with the reverse-bias voltage being any value within the maximum limits of the device.

[Note that for forward bias the voltage across the p-n junction is p-positive, while for reverse bias it is opposite (reverse) with n-positive. This emphasis on the initial letter should provide a means of helping memorize the necessary voltage polarity.]

Operation in the cutoff, saturation, and linear regions of the BJT characteristic are provided as follows:

1. Linear-region operation:

Base-emitter junction forward biased Base-collector junction reverse biased



- Cutoff-region operation: Base-emitter junction reverse biased
- Saturation-region operation:
 Base-emitter junction forward biased
 Base-collector junction forward biased

4.3 FIXED-BIAS CIRCUIT

The fixed-bias circuit of Fig. 4.2 provides a relatively straightforward and simple introduction to transistor dc bias analysis. Even though the network employs an npn transistor, the equations and calculations apply equally well to a pnp transistor configuration merely by changing all current directions and voltage polarities. The current directions of Fig. 4.2 are the actual current directions, and the voltages are defined by the standard double-subscript notation. For the dc analysis the network can be isolated from the indicated ac levels by replacing the capacitors with an opencircuit equivalent. In addition, the dc supply V_{CC} can be separated into two supplies (for analysis purposes only) as shown in Fig. 4.3 to permit a separation of input and output circuits. It also reduces the linkage between the two to the base current I_B . The separation is certainly valid, as we note in Fig. 4.3 that V_{CC} is connected directly to R_B and R_C just as in Fig. 4.2.

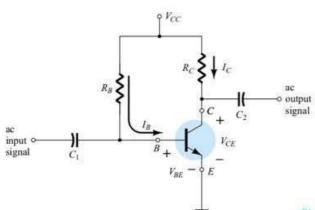


Figure 4.2 Fixed-bias circuit.

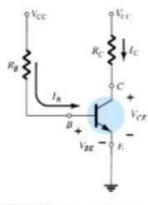


Figure 4.3 dc equivalent of Fig. 4.2.

Forward Bias of Base-Emitter

Consider first the base-emitter circuit loop of Fig. 4.4. Writing Kirchhoff's voltage equation in the clockwise direction for the loop, we obtain

$$+V_{CC}-I_BR_B-V_{BE}=0$$

Note the polarity of the voltage drop across R_B as established by the indicated direction of I_B . Solving the equation for the current I_B will result in the following:

$$I_B = \frac{V_{CC} - V_{BE}}{R_B} \tag{4.4}$$

Equation (4.4) is certainly not a difficult one to remember if one simply keeps in mind that the base current is the current through R_B and by Ohm's law that current is the voltage across R_B divided by the resistance R_B . The voltage across R_B is the applied voltage V_{CC} at one end less the drop across the base-to-emitter junction (V_{BE}).

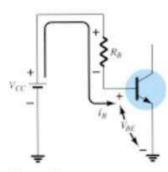


Figure 4.4 Base-emitter loop.



In addition, since the supply voltage V_{CC} and the base-emitter voltage V_{BE} are constants, the selection of a base resistor, R_B , sets the level of base current for the operating point.

Collector-Emitter Loop

The collector-emitter section of the network appears in Fig. 4.5 with the indicated direction of current I_C and the resulting polarity across R_C . The magnitude of the collector current is related directly to I_B through

$$I_C = \beta I_B \tag{4.5}$$

It is interesting to note that since the base current is controlled by the level of R_B and I_C is related to I_B by a constant β , the magnitude of I_C is not a function of the resistance R_C . Change R_C to any level and it will not affect the level of I_B or I_C as long as we remain in the active region of the device. However, as we shall see, the level of R_C will determine the magnitude of V_{CE} , which is an important parameter.

Applying Kirchhoff's voltage law in the clockwise direction around the indicated closed loop of Fig. 4.5 will result in the following:

$$V_{CE} + I_C R_C - V_{CC} = 0$$

$$V_{CE} = V_{CC} - I_C R_C$$
(4.6)

and

which states in words that the voltage across the collector-emitter region of a transistor in the fixed-bias configuration is the supply voltage less the drop across R_C . As a brief review of single- and double-subscript notation recall that

$$V_{CE} = V_C - V_E \tag{4.7}$$

where V_{CE} is the voltage from collector to emitter and V_C and V_E are the voltages from collector and emitter to ground respectively. But in this case, since $V_E = 0$ V, we have

$$V_{CE} = V_C \tag{4.8}$$

In addition, since

$$V_{BE} = V_B - V_E \tag{4.9}$$

and $V_E = 0$ V, then

$$V_{BE} = V_B \tag{4.10}$$

Keep in mind that voltage levels such as V_{CE} are determined by placing the red (positive) lead of the voltmeter at the collector terminal with the black (negative) lead at the emitter terminal as shown in Fig. 4.6. V_C is the voltage from collector to ground and is measured as shown in the same figure. In this case the two readings are identical, but in the networks to follow the two can be quite different. Clearly understanding the difference between the two measurements can prove to be quite important in the troubleshooting of transistor networks.

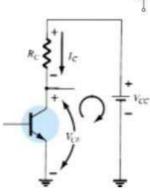


Figure 4.5 Collector-emitter loop.

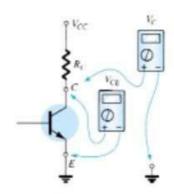


Figure 4.6 Measuring V_{CE} and V_{-}

Determine the following for the fixed-bias configuration of Fig. 4.7.

- (a) I_{B_O} and I_{C_O} .
- (b) V_{CE_O}
- (c) V_B and V_C .
- (d) V_{BC} .

EXAMPLE 4.1